Quantum mean-square predictors of work

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1 Intro

For incoherent quantum systems the *two-point measurement* (TPM) [1] protocol entails the statistics of heat and work. Yet, once applied to initially coherent systems, it erases any coherence in the energy eigenbasis. We propose a partial solution: Giving up measuring the internal energy of the system (S), we develop a predictor of work based on measuring the heat exchanged with the environment (E), while maintaining system's coherence untouched.

2 Formal framework

The energy balance of S + E Hamiltonian

$$H(t) = H_S(t) + H_E + H_{SE},$$
 (1)

implies the $1^{\mbox{\scriptsize st}}$ law

$$\langle W \rangle = \langle Q \rangle + \langle \Delta U \rangle.$$
 (2)

In particular for steady-states, $\langle \Delta U \rangle = 0$ and average heat exactly describes average work.

- Even for steady-states, ΔU generally fluctuates;
- In general, we'd need ΔU and Q to infer W, but measuring ΔU destroys system's coherence;
- We can measure through the TPM $Q(\gamma) = \mu' \mu$, with $\gamma \equiv (\mu, \mu')$ bath's two-time energies;
- Statistical prediction: Finding the function W_{opt}[Q] which minimizes the mean-square error w.r.t. P(W, Q, ΔU);
- P(W,Q, ΔU) is given by a quantum Bayesian network distribution [2];

Main result [3]: The predictor of work which minimizes the Bayesian network mean-squared error is given by

$$\mathcal{W}_{\rm opt}(\gamma) = Q(\gamma) + \frac{\left\langle M_{\gamma}^{\dagger} H_{S}' M_{\gamma} - M_{\gamma}^{\dagger} M_{\gamma} \mathbb{D}(H_{S}) \right\rangle_{\rho_{S}}}{P(\gamma)}, \quad (3)$$

- ρ_S is the initial state of S;
- $\mathbb{D}(\bullet) = \sum_{\alpha} |\psi_{\alpha}\rangle \langle \psi_{\alpha}| \bullet |\psi_{\alpha}\rangle \langle \psi_{\alpha}|$ is the full dephasing operator in the basis of ρ_{S} (not the energy basis!);
- M_{γ} are Kraus components of the open-system dynamics of S (conditioned dynamics);
- $P(\gamma)$ is the TPM probability s.t. $P(Q) = \sum \delta[Q (\mu' \mu)]P(\gamma);$

3 Example: SSDB Heat Engine

$$\frac{d\rho_S}{dt} = -i[H_S, \rho_S] + \kappa f_h D[L_{31}] + \kappa (1 - f_h) D[L_{13}] + \kappa f_c D[L_{21}] + \kappa (1 - f_c) D[L_{12}].$$
(4)

with $L_{ij} = |i\rangle\langle j|$, D Lindblad operators and

$$H_S(t) = \omega_3 |3\rangle\langle 3| + \omega_2 |2\rangle\langle 2| + V(t),$$
(5)

$$V(t) = h(|2\rangle\langle 3|e^{-i\omega t} + e^{+i\omega t}|3\rangle\langle 2|).$$
(6)

We build the predictor with the jump unravelings

$$M_1 = \sqrt{\kappa f_h \Delta t} \ L_{31}, \qquad M_2 = \sqrt{\kappa (1 - f_h) \Delta t} \ L_{13}, \qquad (7)$$

$$M_3 = \sqrt{\kappa f_c \Delta t} \ L_{21}, \qquad M_4 = \sqrt{\kappa (1 - f_c) \Delta t} \ L_{12}, \qquad (8)$$



4 Conclusion

We develop a tool to predict work fluctuations conditioned on heat measurements. Our result can be seen as a first law at the level of *heat* trajectories. We use it to predict work realizations in the SSDB heat engine, whose steady-state is coherent.

References

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